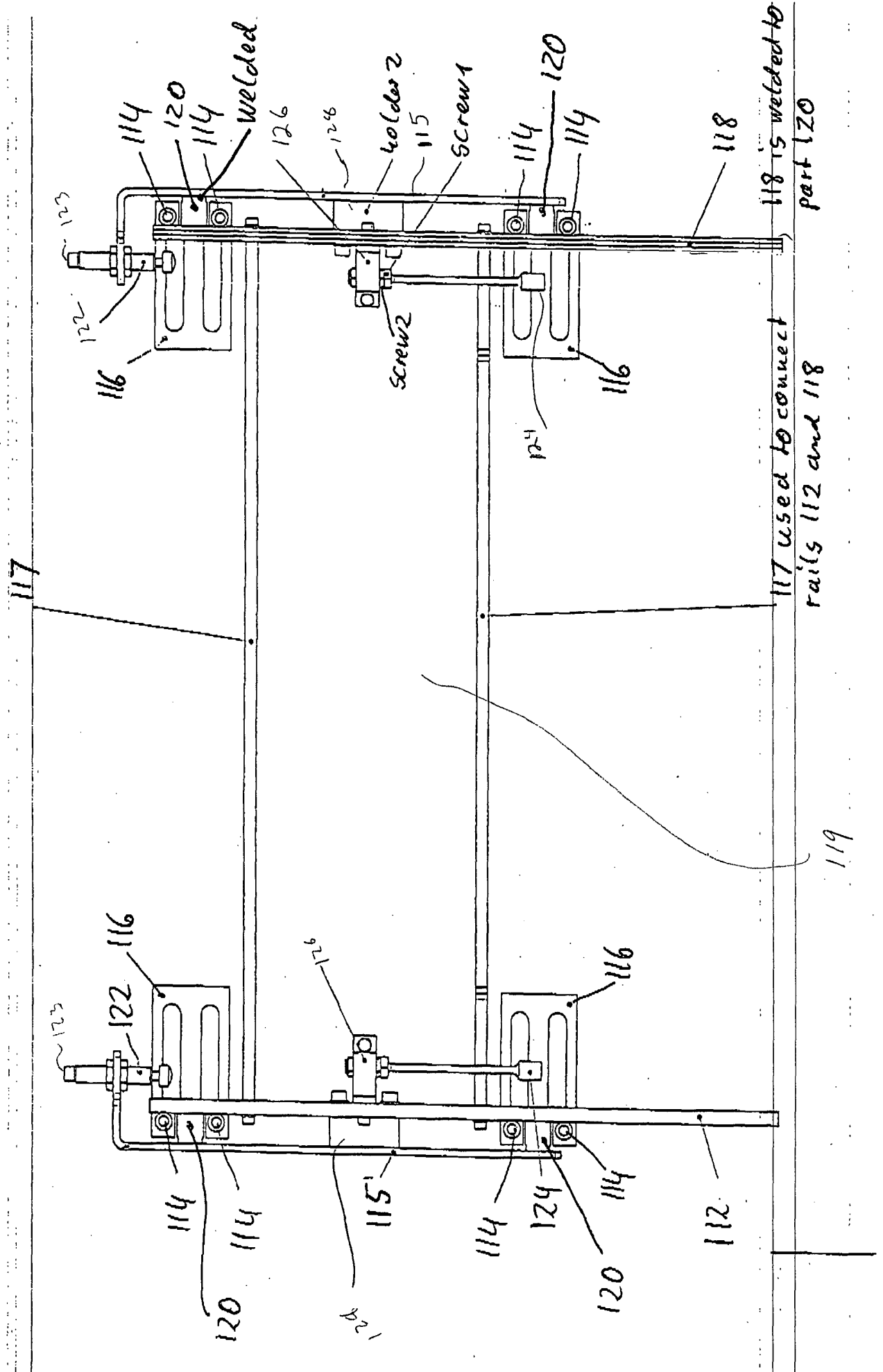


Fig. 1

Fig. 2A



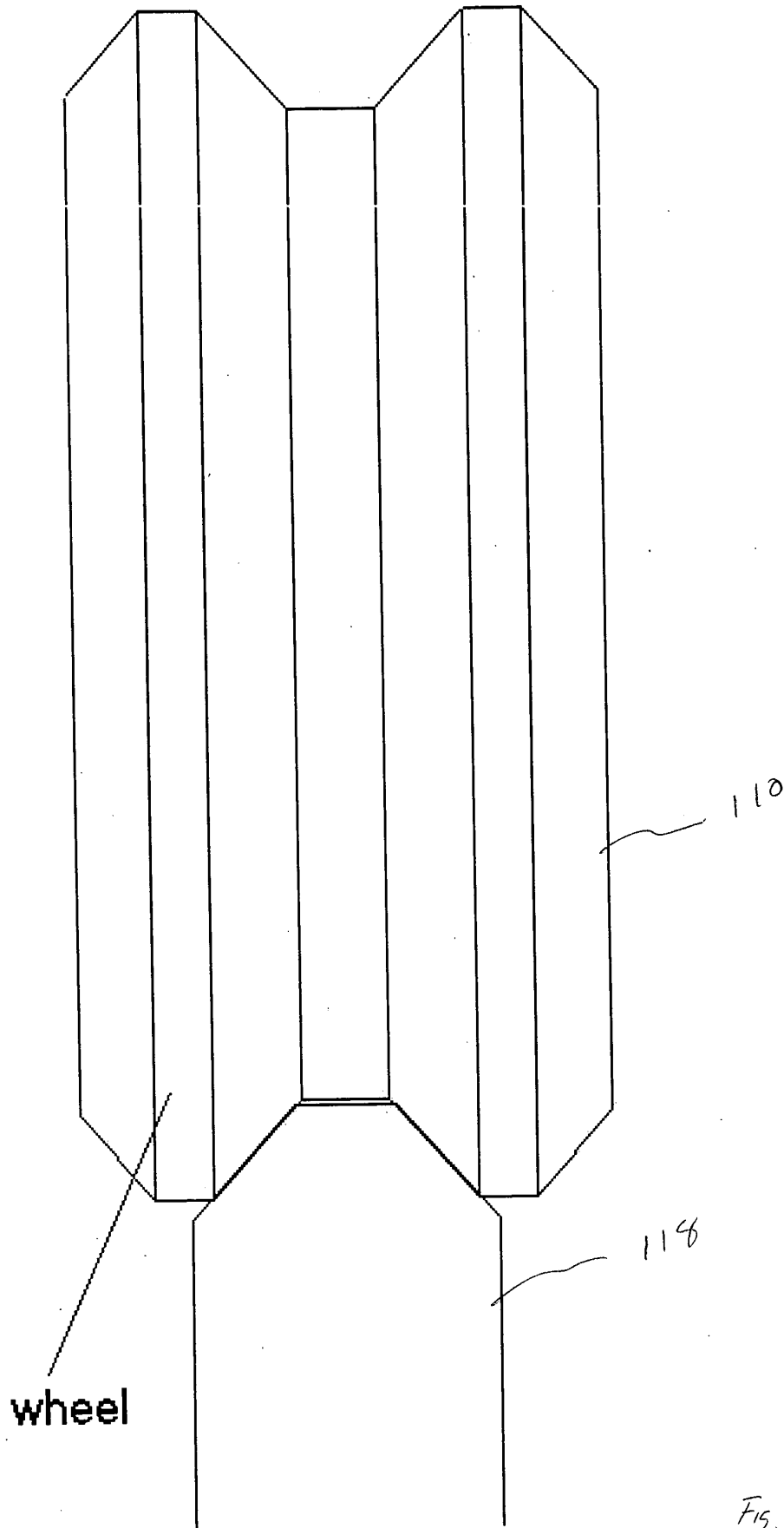


Fig. 2 b

Fig. 2c

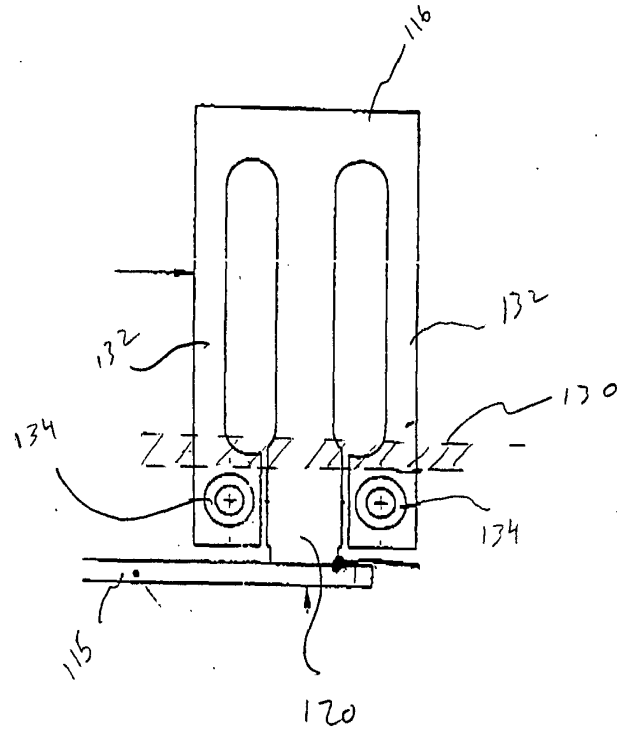


Fig. 2d

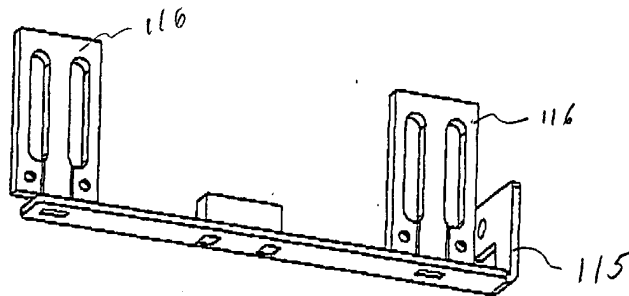
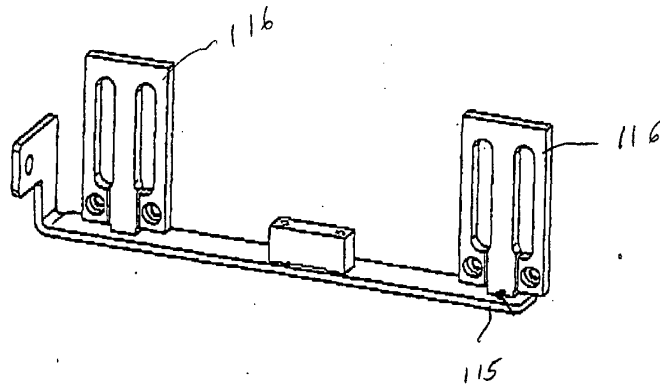


Fig. 2e

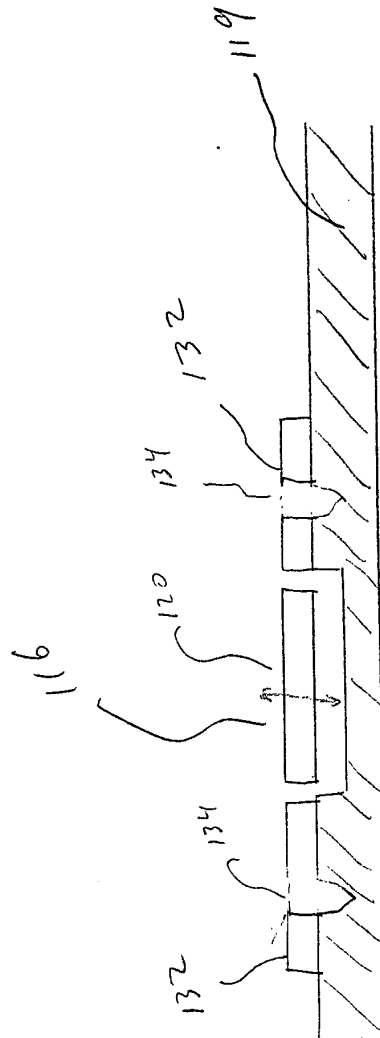


Fig. 2f

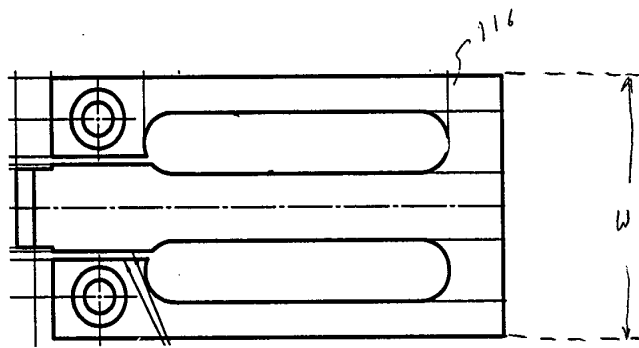


Fig. 2g

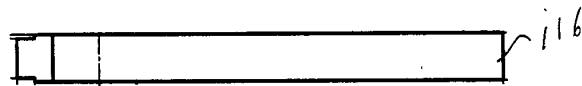


Fig. 2h

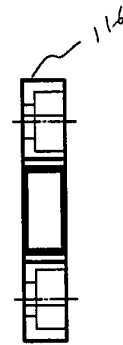


Fig. 2i

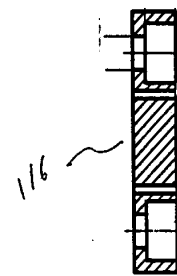


Fig. 2j

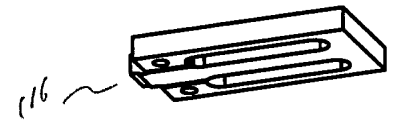
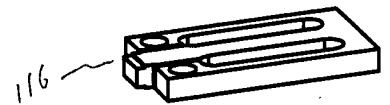


Fig. 2k

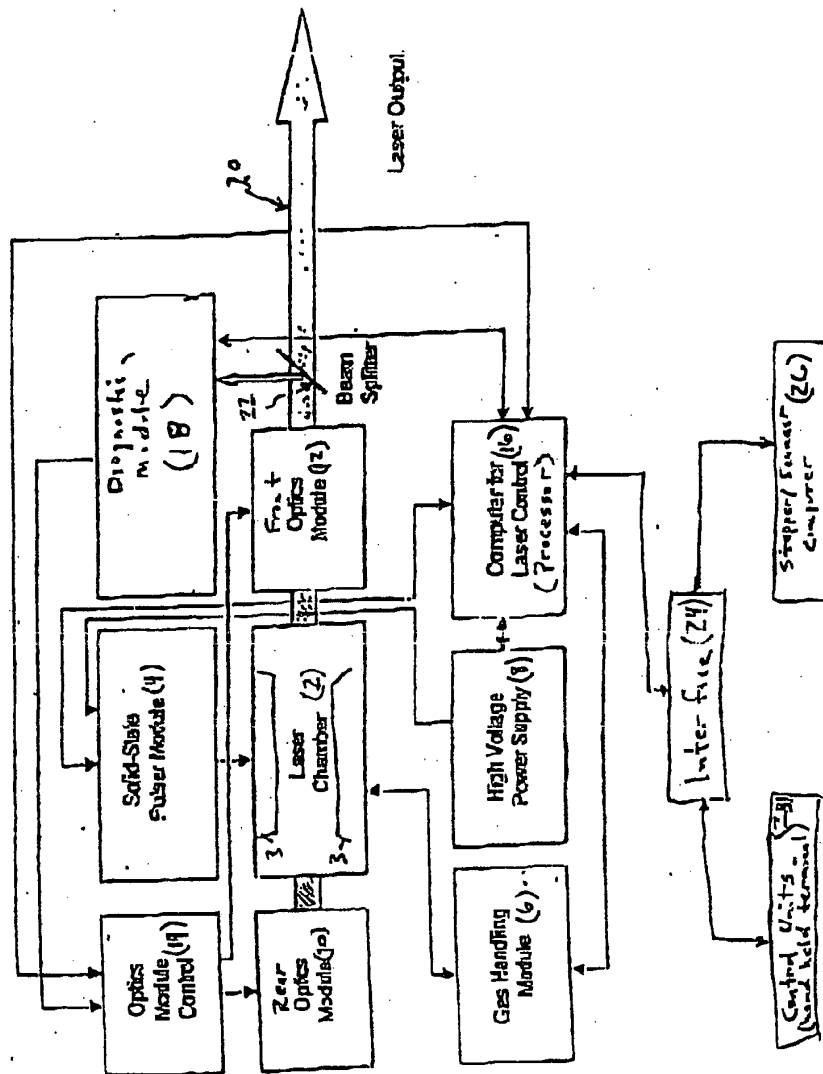


Fig. 3

FIG. 4A

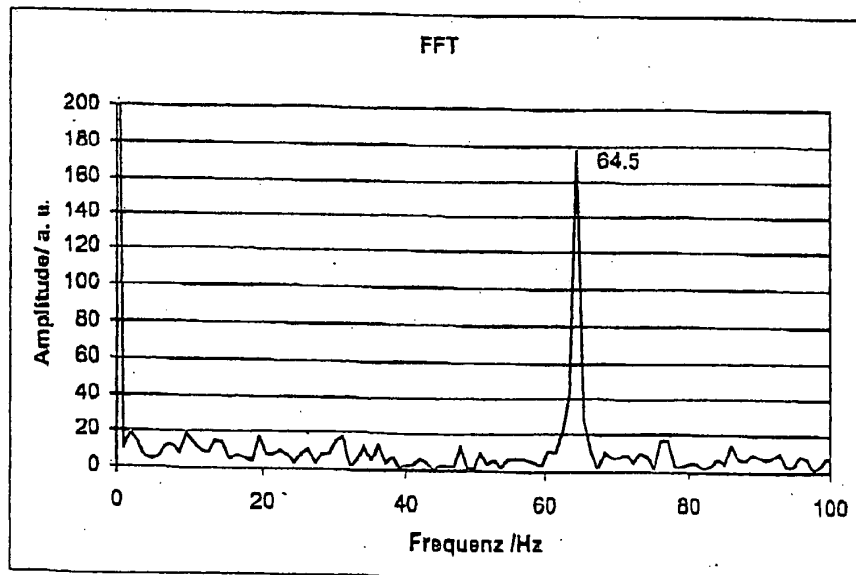
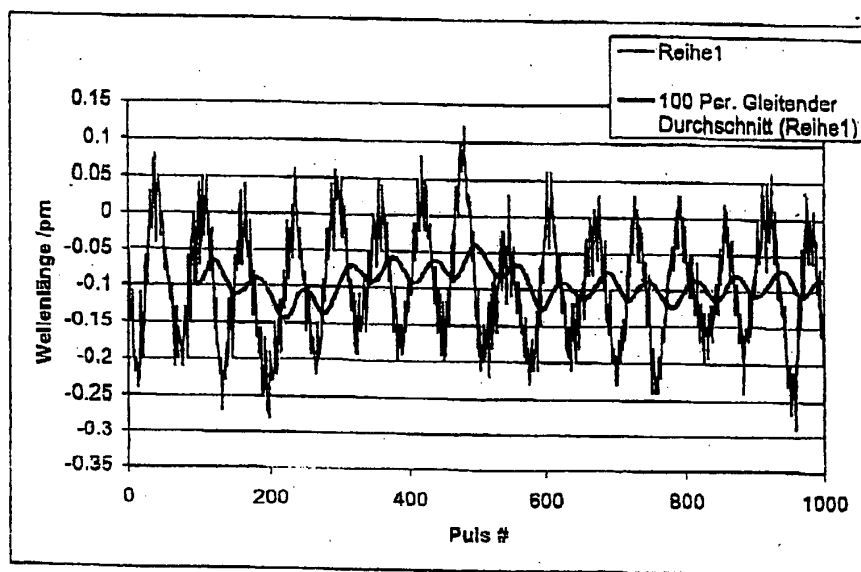


Fig 4b



Fig 5a

wavelength stability A4005 (E6081) with new spring tube  
suspension and standard ROM design, measurement at 4 kHz cw  
without stabilization, 22.5.02

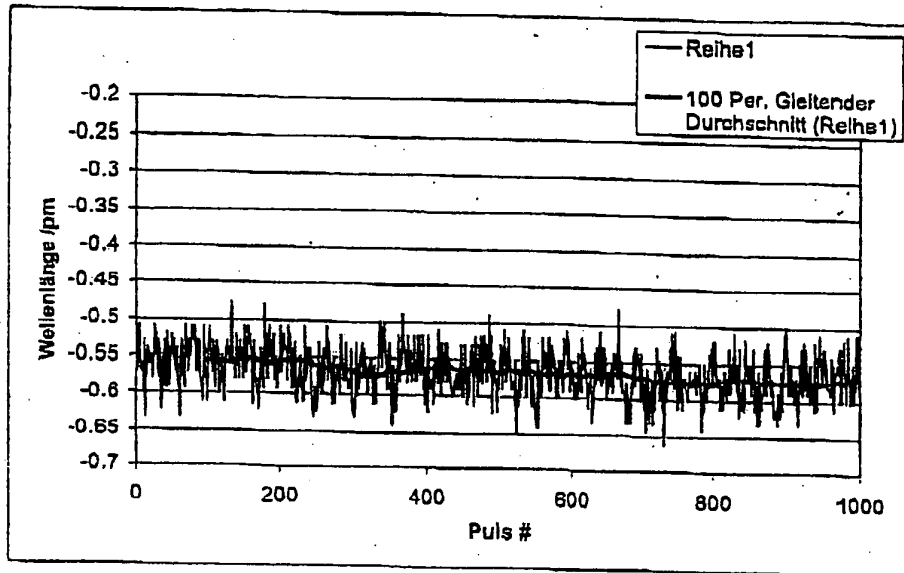
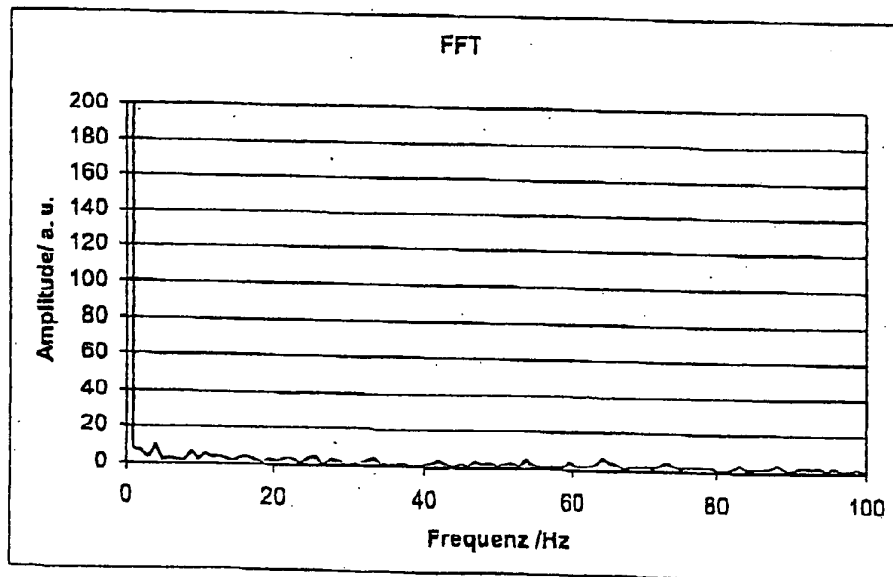
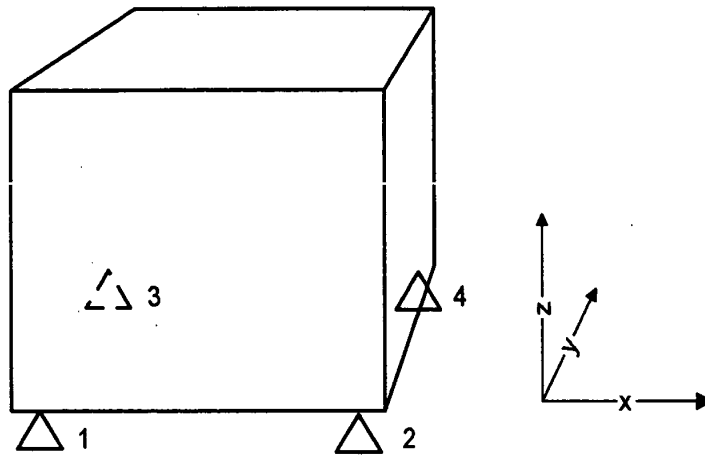


Fig 5b





**Figure 6:** Orientation of axes and numbering of feet. X- and y-axes are to be leveled horizontally. Foot 1 is fixed, foot 2 levels the x-axis, foot 3 levels the y-axis and foot 4 is used for balancing the weight.

Fig. 7

CDU can move up and down, this movement can be minimized by the W-Spring suspension

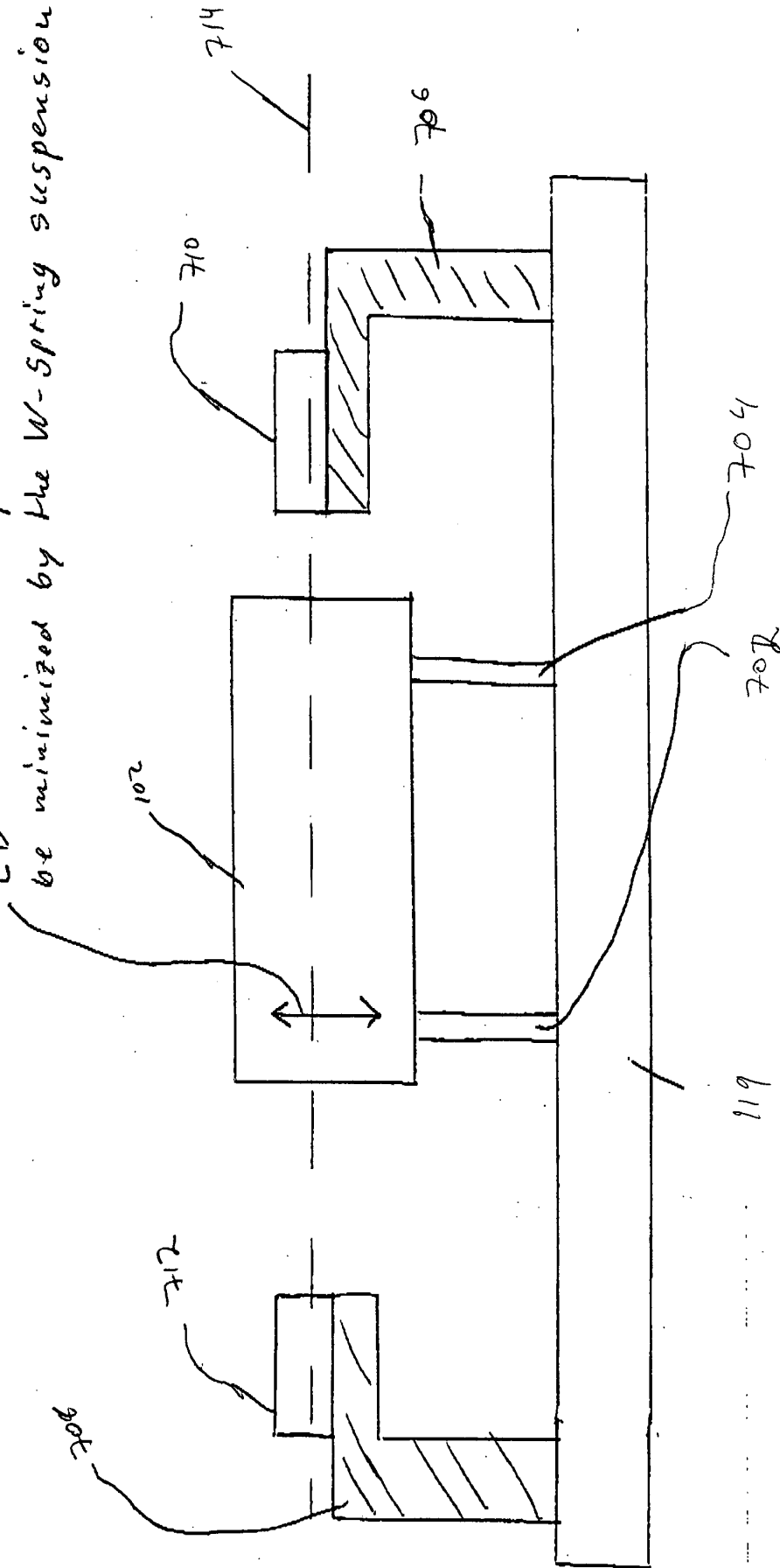


Fig. 2A 8a

atched is the 6D looking from above

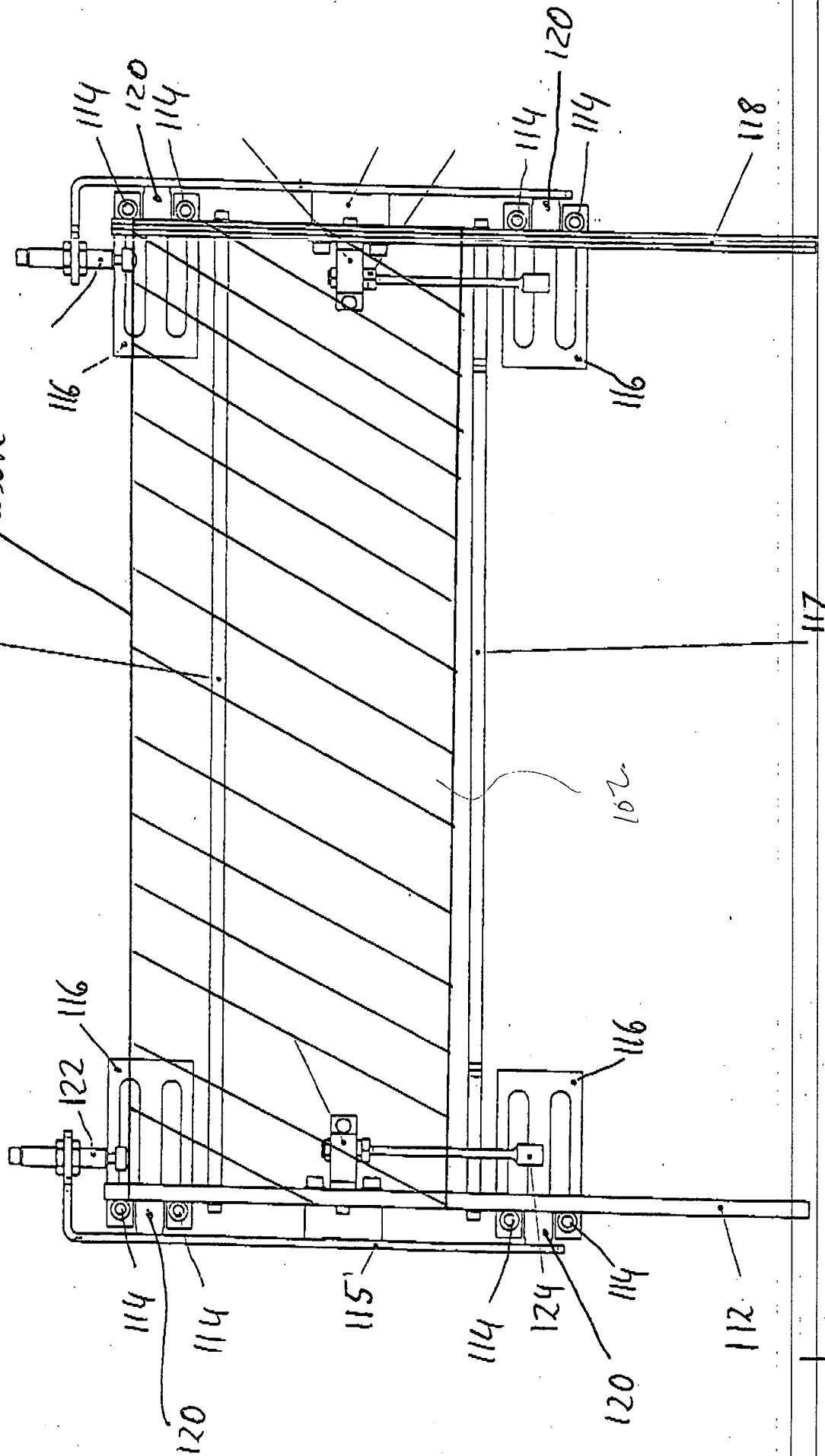


Fig. 8b

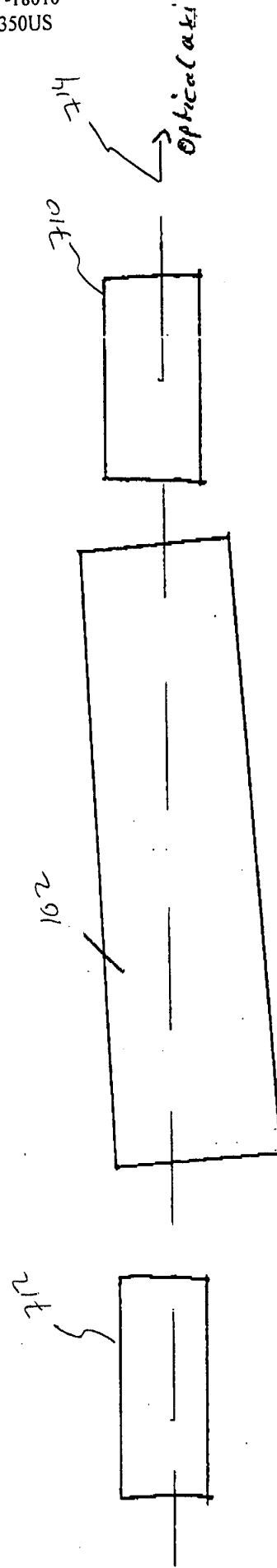
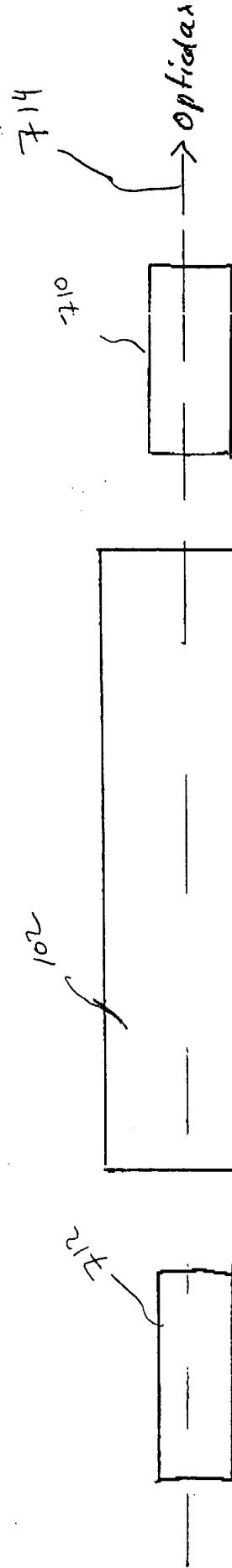


Fig. 8c